Read this entire manual before operation begins.

Record below the following information which is located on the serial number data plate.

Serial No. __________
Model No. __________
Date of Installation __________
Contents

Caution ............................... 5
Intended Use ......................... 7
Operator Training ..................... 8
Machine Composition ................. 9
System Features ...................... 16
Transport And Installation ........... 18
Switching The Machine On And Off 23
Low Battery Indication .............. 26
Program Configuration ............... 27
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Database Customization ............. 58
Program And Database Protection ... 67
Errors During Measurement .......... 71
Troubleshooting ...................... 73
Maintenance ........................... 74
Storage And Scrapping ............... 75
Machine Identification Data .......... 76
## Symbols Used In The Manual

<table>
<thead>
<tr>
<th>SYMBOLS</th>
<th>FORBIDDEN!</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Forbidden" /></td>
<td>Operations or jobs to be performed compulsorily</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><img src="image" alt="Mandatory" /></th>
<th>Mandatory!</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Hazard" /></td>
<td>Hazard!</td>
</tr>
<tr>
<td><img src="image" alt="Bluetooth" /></td>
<td>Bluetooth brands are property of their owners, and are used by Atlas Equipment under license.</td>
</tr>
</tbody>
</table>

Bluetooth brands are property of their owners, and are used by Atlas Equipment under license.
Caution

Any damage caused by failure to follow the instructions in this manual or improper machine use shall relieve Atlas Equipment of all liability.

Preliminary Safety Information

Before starting the machine:

- Read the instructions and the entire manual before using or working on the wheel aligner. This manual represents an integral part of the product and is intended to inform the user on how to use the Atlas Cyclops wheel aligner. Keep the manual for the entire life of the machine. Keep it in an easy to access place and refer to it every time the need arises. All machine operators must be able to read the manual.
- Make sure the power supply is in conformity with the specifications shown on the plate. Voltage and frequency data plate is positioned on machine back side. Please, read plate data. NEVER connect aligner to a voltage or frequency other than the specified ones.
- Duly arrange wheel aligner power cable. This product features a 3-wire plug with built-in grounding. It can be plugged into a socket with built-in grounding, only. Should a grounded socket not be available for machine connection, contact an electrician. Do not tamper with or misuse plug.

Upon machine switching off:

- Do not switch off the built-in PC by unplugging it or by turning PC switch to off, but follow the procedure set forth in part 6.2. Improperly switching off the PC could lead to HARD-DISK files “corruption”.
- The switching off procedure set forth in part 6.2 does not affect battery recharge supports, which continue being powered.
In emergency conditions and before performing any maintenance:

- Insulate the machine against any power source using the special master switch, and remove plug from power socket.
- Do not try to service this unit arbitrarily, as the opening or removal of machine doors could expose user to hazardous voltage. Maintenance operations shall be carried out by authorized service personnel, only.

Work environment and machine cleaning:

- The work environment must be kept clean and dry, and must not be exposed to atmospheric agents. It must also be well lit.
- Do not clean the machine using jets of water and compressed air. To clean plastic panels or surfaces use a moist cloth (avoid using liquids containing solvents).

*Atlas Equipment shall be entitled to make any changes to the models described in this manual at any time for reasons of a technical and commercial nature.*
The Atlas Cyclops system is a machine designed for detection of all vehicle special angles. Applications: double axle cars and light commercial vehicles with wheelbases ranging between 5’ 11” (min.) and 15’ 5” (max.).

Infrared measurements of reciprocal angles are detected by two 3D cameras placed between the front and rear wheels, each fitted with two megapixel cameras which detect the spatial position of 4 three-dimension targets on the wheels (no cable connections). Data is transmitted from 3D cameras to cabin VIA RADIO through Bluetooth.

Machine operational temperature range: 32 to 100°F.
Operator Training

The machine must be used by specifically trained and authorized personnel, only. To ensure proper machine use and that measurements can be efficiently taken, operators must be correctly trained and acquire the skills consistent with the instructions provided by the manufacturer. For any questions on the use and maintenance of the machine, please read the instruction manual or the manuals supplied with the individual pieces of equipment (PC, monitor, printer, ...) and then, if such doubts persist, contact an authorized after-sales center or Atlas Equipment technical assistance directly.

2.1 General Preventive Measures

- During operation and maintenance of this machine, always abide by the safety and accident-prevention regulations in force.
- The machine must only be used by adequately trained and authorized persons.
- This machine must only be used for the purpose for which it was expressly intended. Atlas Equipment declines all liability for injury or damage to persons, animals, and things caused by improper machine use.
- Accessories and spare parts must be fitted by persons authorized by Atlas Equipment and only original spare parts and accessories must be used.
- The machine must only be operated in places where there is no danger of explosions or fire.
- Removal or changes made to safety devices, or warning signals on the machine can cause serious hazards and represent a violation of safety regulations.
- Before doing any maintenance jobs on the system, always disconnect the power supply. In case of doubt, do not interpret, but contact Atlas Equipment technical assistance in order to obtain instructions suitable for performing operations in total safety.
- Do not allow unauthorized personnel to come near the wheel aligner during use.
3.1 Atlas Cyclops Overview

**PC Keypad**
Machine features a 102-key, PC-type command keyboard. Function keys allow using almost all machine functions. Vehicle general data, customer data, and vehicle database customization can also be entered via PC keyboard.

**Printer Central Compartment**
Results are printed with an inkjet color printer. Printer use and maintenance instructions can be found on the manual coming with the printer itself. Comply with these instructions.

**Measurement Cabin**
A measurement cabin is used for all measurement operations. This cabin also features the electronic components necessary for the processing and management of the measurements made by the 3D cameras. Power supply: 220 / 240 Vac single phase 50/60Hz; Maximum absorbed power: 500w

**Monitor**
All models feature high-definition, color monitor 22” 16/9. Use and maintenance instructions can be found on the manual coming with the monitor itself. Comply with these instructions.

**Battery Recharge Support**

**Machine Master Switch**

**Shock Hazard Power Socket**

**Supports**
Four supports for housing the clamps with target
3.2 Managing PC

Software is installed on managing PC (personal computer), positioned inside cabin. EPIA managing PC M830 features:

- Processor VIA Nano 1.3GHz.
- RAM 1 Gb;
- Smart card reader
- 6 USB; 1 LAN Ethernet 10/100Mb;
- Windows 7 operating system, English version
- 1366x768 Pixels HD Ready video output
- Hard Disk ≥ 160 Gb

3.3 3D cameras

The Cyclops 3D cameras do not need any cable or cord connection for angle measurement or data transmission. Detecting units consist of 2 megapixel cameras for each 3D camera. Each camera features a set of high efficiency infrared LED’s, used to light the 3D targets fitted on the wheels of the vehicle.

Data is transmitted directly VIA RADIO through Bluetooth modules located inside the 3D cameras and cabin.

Characteristic angles of both axles of the vehicle are controlled and compensated by 4 CCD sensors and 2 electronic inclinometers located inside the two 3D cameras. Data transmission among infrared 3D cameras is effective also under critical lighting conditions.

Power is supplied by rechargeable 12V long-lasting batteries. Batteries are recharged when they are inserted into the recharge supports located on the cabin (see part 3.1).

WARNING: always switch 3D cameras off upon removing and/or inserting the batteries; manual switch-off is carried out by pressing simultaneously the most external red and green buttons (see part 3.3.1).

For 3D cameras with rechargeable batteries, power supply and consumption data are the following:

<table>
<thead>
<tr>
<th>Power supply</th>
<th>NiMH battery (NICKEL-METAL HYDRIDE) 12V- 4Ah</th>
</tr>
</thead>
<tbody>
<tr>
<td>Average operation with fully effective and charged battery</td>
<td>Approx. 8 hours</td>
</tr>
<tr>
<td>Average recharge time</td>
<td>Approx. 12 hours</td>
</tr>
</tbody>
</table>
GREEN LED: battery under charge / external powering
RED LED: indicating that detector is on

Detector Keypad
(see part 3.3.1)

CCD sensors for reciprocal angle compensation

LED for tolerance indication
(see part 3.3.2)

Megapixel camera with infrared LED lighting

LED indicating battery under charge

3D camera support

Connector for battery recharge/external powering

3D camera coupling plate

Figure 1
### 3.3.1 3D camera keypads

- **Alphanumeric display**
  - Indicates battery charge in %

- **Figure 2**

<table>
<thead>
<tr>
<th>KEYS</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Key Icon]</td>
<td>Main switch-on key.</td>
</tr>
<tr>
<td>![Left Green]</td>
<td>When pressed simultaneously, they turn head manually off.</td>
</tr>
</tbody>
</table>

#### Legend of Figure 2:

- **A** - Green LED on: Power is supplied.
- **B** - Red LED steady on: The 3D camera is ON
- Red LED flashing: Battery of 3D camera is flat (when battery residual charge is lower than or equal to 30%); it will turn off after a few minutes

### 3.3.2 LED indicating tolerance during adjustment

The 3D cameras (see part 3.3) feature LED tolerance indicators during adjustment.

- **Tolerance indicator during adjustment**
  - **GREEN LED flashing** → measurement is within tolerance, exactly at the center
  - **RED LED flashing and GREEN LED steady on** → measurement is within tolerance
  - **RED LED on** → measurement is NOT within tolerance
NOTE: Toe-in tolerance is always indicated by the lower LED row.

During rear adjustment, camber is always indicated by the upper LED row.

During front adjustment, both camber and caster can be indicated by the upper LED row. The “R” selection symbol should be set on the desired value (see 9.12).

3.4 Clamps with target

The self-centering clamps with removable tabs will be fitted with a target (see Figure 3).

3-point self-centering resting clamps, fitted with targets (for rims from 8” to 24”)

Figure 3
They are marked as Front Left and Right and Rear Left and Right, according to the following table (see Figure 4):

<table>
<thead>
<tr>
<th>FL = FRONT LEFT</th>
<th>FR = FRONT RIGHT</th>
</tr>
</thead>
<tbody>
<tr>
<td>RL = REAR LEFT</td>
<td>RR = REAR RIGHT</td>
</tr>
</tbody>
</table>

Warning: the inclination of the target is determined at installation time, as described in the part 5.2.3. Once the target is fixed, fasten the clamps to the wheel, making sure to position them vertically (see figure above).

Each target features a barcode as well, describing the characteristics of the 3D object.

Clamp + target calibration and progressive production number for traceability, are included also in the above code.

![Figure 4](image)

**Figure 4**

3D object characterization in space

Graphic symbol sticker that shows the position (see part 5.2.2), applied both on target on clamp
3.5 Pedal depressor

The pedal depressor is a tool used to lock the brake pedal during preliminary measurement operations. It has to be used as shown in the instructions displayed during program.

3.6 Steering lock

The steering lock is a tool used to keep vehicle steering in a fixed position. It is used before the adjustment procedure, as shown by the instructions displayed during program.
4.1 Safety Devices

The Cyclops features a master switch positioned on the rear of the machine. The master switch cuts off machine power when set to “0”.

4.2 Measurement Range and Accuracy

<table>
<thead>
<tr>
<th>Axle</th>
<th>Measurement</th>
<th>Accuracy</th>
<th>Measurement Range</th>
<th>Measurement Total Range</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Front</strong></td>
<td>Toe</td>
<td>± 2’</td>
<td>± 2°</td>
<td>± 20° x 2</td>
</tr>
<tr>
<td></td>
<td>Partial toe</td>
<td>± 1’</td>
<td>± 1°</td>
<td>± 20°</td>
</tr>
<tr>
<td></td>
<td>Set-back</td>
<td>± 2</td>
<td>± 2°</td>
<td>± 5°</td>
</tr>
<tr>
<td></td>
<td>Camber</td>
<td>± 2’</td>
<td>± 3°</td>
<td>± 10°</td>
</tr>
<tr>
<td></td>
<td>Caster</td>
<td>± 5’</td>
<td>± 10°</td>
<td>± 18°</td>
</tr>
<tr>
<td></td>
<td>Kingpin</td>
<td>± 5’</td>
<td>± 10°</td>
<td>± 18°</td>
</tr>
<tr>
<td><strong>Rear</strong></td>
<td>Toe</td>
<td>± 2’</td>
<td>± 2°</td>
<td>± 20° x 2</td>
</tr>
<tr>
<td></td>
<td>Partial toe</td>
<td>± 1’</td>
<td>± 1°</td>
<td>± 20°</td>
</tr>
<tr>
<td></td>
<td>Set-back</td>
<td>± 2’</td>
<td>± 2°</td>
<td>± 5°</td>
</tr>
<tr>
<td></td>
<td>Camber</td>
<td>± 2’</td>
<td>± 3°</td>
<td>± 10°</td>
</tr>
<tr>
<td></td>
<td>Thrust angle</td>
<td>± 2’</td>
<td>± 2°</td>
<td>± 5°</td>
</tr>
</tbody>
</table>
4.3 Overall Dimensions

Figure 6
Transport And Installation

5.1 Transport and unpacking

The machine is supplied packed in a box fastened to a pallet to facilitate transport. To transport the machine to the point where it is to be installed, use a lifting and transport mechanism such as a fork-lift truck or lift with forks.

The machine must be stored in its packaging, in a dry and ventilated environment (with a temperature between -25° +55°C).

Never overturn or position the packaging horizontally. The pallet must always rest on a flat and solid surface. Do not stack other packages on top of the packaging. Always position so the instructions can be easily read.

DURING UNPACKING, ALWAYS WEAR GLOVES TO PREVENT ANY INJURY CAUSED BY CONTACT WITH PACKAGING MATERIAL (NAILS, ETC.).

Make sure you have received all standard parts as previously listed.

The packaging material (plastic bags, polystyrene, nails, screws, wood, etc.) must be collected up and disposed of through authorized channels, except for the pallet, which could be used again for subsequent machine handling.

5.2 Installation

Install the machine in a dry, covered and well-lit place, possibly closed or protected against the elements.

Before positioning the machine, make sure the place chosen complies with applicable safety regulations and check the minimum distances from walls or other obstacles.
### 5.2.1 Power connections

Before connecting up the machine, carefully check:

- power line specifications correspond to machine requirements as shown on the machine plate;
- there is a ground wire the same or greater in length as max section of the power cables.
- that all the component parts of the power line are in good condition;

Connect the machine up by means of the 3-prong plug into a wall socket or a surge protector.

### 5.2.2 Clamp/Target Mounting

Targets have to be mounted onto wheel clamps at an angle of 20°. To do this accurately, adopt the following procedure:

![Figure 7](image_url)

Mount targets onto wheel clamps at an angle of approximately 20° and fit them to the vehicle. Make sure that wheel clamps are secured in place with the spokes positioned strictly vertically (12 o’clock), as shown in Figure 7.

In the menu item “Configuration” select the option “target assembly”.

As soon as targets are in place and have been optimized, the screen represented in figure 8 will appear.

Carefully align the 4 targets by matching the arrows with the targets above. If
one or more targets are not properly orientated, an “X” symbol will appear (see the rear-left wheel clamp in the example below). At the end of the alignment procedure block the grub screw with the lock nut.

Figure 8

Apply the two stickers provided for each wheel clamp/target combination which identify the front left (FL), front right (FR), rear left (RL) and right rear (RR) positions. (See Figure 4)

5.2.3 Mounting the 3D camera unit supports

In order to be able to fit the 3D camera unit supports, it is necessary to drill two M8 holes on each side of the vehicle lift. This should be done in such a way that the distance from the center of the 3D camera units to the center of the turn plates is 3’ 11”.

If you need to work on vehicles with long wheelbases, turn plates can be moved forward up to another 1’ 3”. The maximum distance from the rear wheels to the center of the 3D camera units is 10’ 2”.

The figure below shows the left and right hand camera unit mounting bracket hole patterns. Note: The distance from the center of the plate is slightly different (1/2”). This is due to the asymmetry of the support itself with respect to the two holes.
WARNING: Before switching the machine on, make sure that the SMART CARD for program enabling and the database are in the special reader on PC front side (see part 11).

6.1 Switching the Machine On

To switch the machine on and to gain access to the program, turn the master switch positioned on machine back side.

Once PC initialization is completed by Windows operating system, the program will be automatically enabled and the introduction page will be displayed. From this page you can enable all machine functions (see part 9).

Figure 10
### 6.2 Switching the Machine Off

From the introduction page (see part 9) you can switch the machine off by selecting the corresponding key.

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>PC Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Detector Keypad" /></td>
<td><img src="image2" alt="PC Keypad" /></td>
<td>It enables machine switching off procedure request</td>
</tr>
</tbody>
</table>

![Figure 11](image3)

You then have a chance to confirm your choice:

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>PC Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image4" alt="Detector Keypad" /></td>
<td><img src="image5" alt="PC Keypad" /></td>
<td>It cancels. It goes back to the introduction page. (part 9)</td>
</tr>
<tr>
<td><img src="image6" alt="Detector Keypad" /></td>
<td><img src="image7" alt="PC Keypad" /></td>
<td>Final confirmation of machine switching off</td>
</tr>
</tbody>
</table>
Then turn the machine off with the switch positioned on machine back side.

**WARNING:** The switching off procedure does not affect battery recharge supports, which continue being powered.

The system makes the 3D cameras switch off when the PC is switched off from the introduction page. 3D cameras will anyway automatically switch off after approximately 5 minutes if no data are received (ex. cabin is off). They can also be manually switched off (see part 3.4.2) when they are not needed.
Low Battery Indication

System displays a low battery warning signal (Figure 13).

This signal is also visible on the 3D camera itself through the flashing of start RED LED (see part 3.4.2).

![Right 3D Camera](image)

Figure 13

When the charge is LOWER than or EQUAL to 30%, system displays the page of low battery indication (Figure 13). The camera will automatically switch off after a few minutes. Try not to reach this condition, and charge batteries as soon as possible.

To quit the signal page, press F1 🎮.
To proceed to program configuration, select F2 from the introduction page, as explained in part 9.1.

You will enter a configuration menu allowing edits to the different program characteristics according to your needs.

**Figure 14**

Language selection: You can select your dialogue language among the many available ones.

Configuration: Program will display the screen of Figure 15.

You can edit system parameters, database profile, specify which parts are fitted on the machine, parts type, and make a Bluetooth search to couple the 3D cameras with cabin.

Print Menu: Print can be customized by entering workshop data, selecting the type of desired printout, and selecting the pre-set printer (if more than one printer is connected).
Backup / Restore: In order not to run the risk of losing any vehicle and customer database data, it is recommended to create a backup copy (data saving). We recommend using a “flash disc” USB key for this process. Lost or deleted data can be restored if the backup operation has been carried out, thanks to the restore procedure.

Additional functions: program displays screen Figure 58, from which you can access TEST or sensor Calibration applications (reserved to skilled and authorized personnel), and the “DATABASE MANAGEMENT” (see part 11).

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>PC Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Detector Keypad]</td>
<td>![PC Keypad]</td>
<td>It goes back to the introduction page. (part 9.1)</td>
</tr>
<tr>
<td>![Detector Keypad]</td>
<td>![PC Keypad]</td>
<td>It moves selection up.</td>
</tr>
<tr>
<td>![Detector Keypad]</td>
<td>![PC Keypad]</td>
<td>It moves selection down.</td>
</tr>
<tr>
<td>![Detector Keypad]</td>
<td>![PC Keypad]</td>
<td>It confirms selection.</td>
</tr>
</tbody>
</table>

### 8.1 DATABASE Groups Configuration

Select “GROUPS CONFIGURATION” from program configuration page, as explained in part 8 You can edit system parameters, database profile, and specify which parts are fitted on the machine, and parts type as well.
Figure 15

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>PC Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Back Arrow]</td>
<td>![Back Arrow]</td>
<td>![F1 Back Arrow]</td>
</tr>
<tr>
<td>![Up Arrow]</td>
<td>![Up Arrow]</td>
<td>![F2 Up Arrow]</td>
</tr>
<tr>
<td>![Down Arrow]</td>
<td>![Down Arrow]</td>
<td>![F3 Down Arrow]</td>
</tr>
<tr>
<td>![Forward Arrow]</td>
<td>![Forward Arrow]</td>
<td>![F4 Forward Arrow]</td>
</tr>
</tbody>
</table>

Select “DATABASE” option, and confirm. The following screen will be displayed:
Page Figure 16 displays a list, with the different DATABASE profiles, including the MAKES of the vehicles circulating in the different countries and regions all over the world.

Using key F5 , you can hide and/or display any profile so as to manage Database according to your needs.
By selecting any group and pressing F4 you can also customize your profile by hiding and/or displaying the available makes, with key F5.
9.1 Introduction Page

Upon machine switching on (see part 6.1), the program start screen will be displayed. You can select different functions.

![Figure 19]

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>PC Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Detector Keypad" /></td>
<td><img src="image2" alt="PC Keypad" /></td>
<td>F1</td>
</tr>
<tr>
<td><img src="image2" alt="PC Keypad" /></td>
<td><img src="image2" alt="PC Keypad" /></td>
<td>F2</td>
</tr>
<tr>
<td><img src="image2" alt="PC Keypad" /></td>
<td><img src="image2" alt="PC Keypad" /></td>
<td>F3</td>
</tr>
<tr>
<td><img src="image2" alt="PC Keypad" /></td>
<td><img src="image2" alt="PC Keypad" /></td>
<td>F4</td>
</tr>
</tbody>
</table>

Press F4 to continue.
9.2 Preliminary Operations

9.2.1 Vehicle Check Preliminary Operations

Before starting the vehicle alignment, the following checks should be carried out:

- Check and, if necessary, eliminate any clearance on suspensions on steering linkage
- Check and, if necessary, eliminate any hard spot or yielding of suspension spring parts.
- Adjust tire pressure to the values specified by the manufacturer.
- Position and distribute any load envisaged by the manufacturer.

9.2.2 Measurement Preliminary Operations

Before proceeding with the selection of the page showing the technical data of the vehicle (see part 9.4), you can start preparing the vehicle for measuring as described below:

- Properly place the vehicle with the front wheels on the rotating plates
- Fit clamps with the four targets onto wheels
- Connect and switch on the 2 3D cameras on lift edges (see Figure 1)
- Lock rotating plates

In this phase, the pictures showing the 2 batteries of the 3D cameras are displayed with the relevant residual charge %. In the case of models which do not feature a battery and are therefore powered by cable, or when the recharge cable is connected, the charge % will always show 99%.

---

1 It is recommended to mount the clamps with the targets and switch on the 2 3D cameras already in the preliminary stage, to enable the system to recognize and “connect” the 4 targets located on the wheels. The time taken by the following phase for selecting make and model and for displaying technical data is therefore used by the system also for the recognition and optimization of the 4 targets.
Figure 20

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>PC Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Arrow left]</td>
<td>![F1]</td>
<td>It goes back to previous page</td>
</tr>
<tr>
<td>![Arrow right]</td>
<td><img src="arrow_right.png" alt="" /></td>
<td>It continues on next page (Selection of Make and Model) (part 9.3)</td>
</tr>
</tbody>
</table>

The system takes some seconds to complete the correct target recognition. During this phase and during the following measuring phases, the symbols displayed on the bottom right side of the screen show the progress of the 4 target recognition. See legend below.

- \(\bullet\) = Target NOT recognized (GREY symbol)
- \(\square\) = Target recognized and in the process of being optimized (GREY symbol)
- \(\blacktriangle\) = Target recognized and optimized / invalid measures (YELLOW symbol)
- \(\blacktriangledown\) = Target recognized and optimized / valid measures (GREEN symbol)
- \(\bullet\bullet\) = Target not required in this phase (BLACK symbol)
ALWAYS take special care when positioning the vehicle on the lift. It should be as centered as possible to speed up and optimize both target search and connection and the following measuring operations.

### 9.3 Vehicle Make and Model Selection

To select vehicle make and model, press ▶️ from the introduction page (Figure 19)

![List with different database profiles (part 8.1)](image)

Press F4 ▶️ to select vehicle make and model of the selected group (see Figure 21).

Selected Vehicle Make

![Selected Vehicle Make](image)

Selected Vehicle Model

![Selected Vehicle Model](image)
Make and model of the vehicle you are going to work on shall be compulsorily selected.

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="←" /></td>
<td><img src="image" alt="F1" /></td>
<td>It goes back to the introduction page (part 9.1)</td>
</tr>
<tr>
<td><img src="image" alt="↑" /></td>
<td><img src="image" alt="F2" /></td>
<td>It moves selection up.</td>
</tr>
<tr>
<td><img src="image" alt="↓" /></td>
<td><img src="image" alt="F3" /></td>
<td>It moves selection down.</td>
</tr>
<tr>
<td><img src="image" alt="→" /></td>
<td><img src="image" alt="F4" /></td>
<td>It confirms selection and goes to the following phase</td>
</tr>
<tr>
<td><img src="image" alt="Page Up" /></td>
<td></td>
<td>It moves selection up by one page.</td>
</tr>
<tr>
<td><img src="image" alt="Page Down" /></td>
<td></td>
<td>It moves selection down by one page.</td>
</tr>
<tr>
<td><img src="image" alt="Home" /></td>
<td></td>
<td>It moves selection to list top.</td>
</tr>
<tr>
<td><img src="image" alt="End" /></td>
<td></td>
<td>It moves selection to list bottom.</td>
</tr>
</tbody>
</table>

NOTE: To speed up selection phase, you can type the name of vehicle make or model, or part of them, on the PC keyboard, and then scroll the list until finding the desired one.
9.4 Selected Vehicle Technical Specification Displaying

When selecting a vehicle (see part 9.3), a page showing the measurements and tolerances supplied by the manufacturer is displayed.

![Vehicle Specification Display](image)

**Figure 24**

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Left Arrow]</td>
<td>![F1]</td>
<td>It goes back to vehicle selection (part 9.3)</td>
</tr>
<tr>
<td>![Reset]</td>
<td>![F2]</td>
<td>See (*) Key description</td>
</tr>
<tr>
<td>![Percentage]</td>
<td>![F5]</td>
<td>It displays vehicle technical specifications next page, and any graphic animation. See (*) Key description</td>
</tr>
<tr>
<td>![Diameter]</td>
<td>![F3]</td>
<td>It changes rim diameter value</td>
</tr>
<tr>
<td>![Next]</td>
<td>![F4]</td>
<td>It goes to out-of-center operations (part 9.5)</td>
</tr>
</tbody>
</table>

(*) Key description
9.5 Thrust Out-of-center with Automatic Acquisition

The out-of-center procedure proves useful to compensate for rim and clamp unbalance, however it is rare that you will need to.

This procedure can be enabled also after having diagnosed the vehicle, by selecting the special option from menu (see part 9.2 - Preliminary Operations). To carry out the out-of-center procedure, you should have performed the preliminary operations, as explained in part 9.2.2.

The clamps must be positioned with the targets at approximately “12 o’clock”, so that during run-out they are always clearly visible to the cameras. If one or more positions are not acceptable, the error message screen indicated below appears, which shows an example of an improperly positioned rear right clamp. Simply position the clamp at “12 o’clock”: the program will proceed automatically.

If instead you press F1, the error is not considered. You may not be able to complete the procedure when performing the run-out.

Figure 25
Press F4 → in the technical data display phase (see part 9.4). The following screen will be displayed:

To carry out the thrust out-of-center operation, it is recommended to carefully follow the displayed instructions.

The starting point is acquired a little further ahead, so that it always remains inside the tables also on the second point, thus avoiding any small gaps.

**Figure 26**
When you are in the first position (approximately 15° forward on turn-tables), press F5 or the central key on one of the two 3D cameras.

“STOP” is displayed for about three seconds, i.e. the time needed by the program to take the measurements from the 1st point, after that, the program shows the following page:

Figure 27

Start moving the vehicle backward, very slowly, until the vehicle arrow matches the target point.

Figure 28
As soon as the vehicle matches the target point, “STOP” is displayed for about three seconds, i.e. the time needed by the program to take the measurements, after that, the program shows the following page:

**Figure 29**

Move vehicle forward again, until vehicle arrow matches target point (final point). “STOP” will be displayed for approx. three seconds, and measurement readings acquired. The thrust out-of-center procedure has been completed.

**Figure 30**
Should you be willing to repeat the operation once the program has already entered a following phase, you can go back to this page by pressing F1, and repeat the above procedure. Once the out-of-center procedure has been completed, the program will automatically go to the next phase.

9.6 Measurement Preliminary Operations

After having carried out the out-of-center procedure as explained in part 9.5, it is necessary to prepare the vehicle for measurement operations. The following screen will be displayed:

1. Release front plates, and any rear platform
2. Brake wheels with hand brake, then lock brake pedal with the pedal depressor tool (this operation is necessary when carrying out a steering for kingpin correct calculation).
3. Settle vehicle front and rear ends (necessary only if vehicle had been previously lifted and the suspensions unloaded).

Figure 31
<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>[←]</td>
<td>It goes back to Out-of-center (part 9.5)</td>
</tr>
<tr>
<td>[→]</td>
<td>F1</td>
<td>It continues to the alignment procedure (part 9.7)</td>
</tr>
</tbody>
</table>

Press [→] to continue.

9.7 Vehicle alignment / direct measurement operations

To proceed to vehicle alignment and direct angle detection, you should have first carried out measurement preliminary operations, as explained in part 9.6.

![Figure 32](image)

When the alignment has been achieved, the “STOP” symbol is displayed, signaling that the program is taking the vehicle measurements. The program proceeds automatically only after the wheels have been aligned.
9.8 Steering Procedure

After wheels have been aligned (see part 9.7), the steering procedure can be carried out in order to define:

- Caster
- Kingpin
- Included angle

Figure 33

<table>
<thead>
<tr>
<th>DETECTOR KEYPAD</th>
<th>PC KEYPAD</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Steering Target Point" /></td>
<td><img src="image" alt="F1" /></td>
<td>Repeat alignment and leveling procedure (part 9.7)</td>
</tr>
<tr>
<td><img src="image" alt="20°" /></td>
<td><img src="image" alt="F2" /></td>
<td>Press this key to select the type of steering to be made. (*)</td>
</tr>
<tr>
<td><img src="image" alt="F4" /></td>
<td></td>
<td>It displays vehicle diagnosis page (part 9.9)</td>
</tr>
</tbody>
</table>

(*) Type of steering to be made:

- Steering at 20°
- ACK steering (at 20° with steering geometry)
- Steering at 10°
- Max. steering
Steering procedure can also be skipped: the values of the above-specified data measurements will not be available. To skip the procedure, press F4 to directly display vehicle diagnosis page.

Should the procedure not be carried out at this stage but only at the end of adjustments, you can select the corresponding option from the menu.

### 9.9 Vehicle Diagnosis

After carrying out the steering procedure (see part 9.8), a diagnosis page showing a summary of the operations carried out on vehicle rear axle (Figure 34) will be displayed.

![Diagram showing vehicle diagnosis page](image)

**Figure 34**
<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Image]</td>
<td>![Image]</td>
<td>Repeat steering procedure. (part 9.8)</td>
</tr>
<tr>
<td>![Image]</td>
<td>![Image]</td>
<td>It changes values displaying layout</td>
</tr>
<tr>
<td>![Image]</td>
<td>![Image]</td>
<td>Selection of diagnosis data display in 1 / 2 pages.</td>
</tr>
<tr>
<td>![Image]</td>
<td>![Image]</td>
<td>It displays vehicle technical specifications (it may be changed, if needed). (part 9.4)</td>
</tr>
<tr>
<td>![Image]</td>
<td>![Image]</td>
<td>It displays diagnosis page with a summary of front axle measurements (Figure 35)</td>
</tr>
</tbody>
</table>

Press F5 🔄 to change diagnosis data display preferences, i.e. on 1 or 2 pages (rear and front). The selection will be stored for the next diagnosis.

Press F4 to display the diagnosis page with a summary of front axle measurements (Figure 34). If you press F3 from here 🚗, program will allow the printout of diagnosis measurements. Press F4 to continue with data adjustment, program will display Figure 35, press F4 again to confirm.

![Figure 35](image)
The vehicle can now be prepared for adjustment (see part 9.10), by pressing F4 to confirm (Figure 36).

9.10 Adjustment Preliminary Operations

By selecting F4 from Figure 36 (see part 9.9), it is necessary to carry out adjustment preliminary operations. Follow the displayed instructions to carry out adjustment preliminary operations. Press F4 to continue.

1. Place steering wheel in straight position.
2. Lock steering wheel with steering lock tool, and continue.

Figure 37
9.11 Rear Axle Adjustment

Rear axle adjustment procedure can be made by pressing F4 from Figure 37 after carrying out adjustment preliminary operations (part 9.10).

Proceed to adjustment, where allowed, as follows:

- Rear camber - Rear partial toe

![Figure 38](image-url)

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image-url" alt="Detector Keypad" /></td>
<td><img src="image-url" alt="Pc Keypad" /></td>
<td>F2</td>
</tr>
<tr>
<td><img src="image-url" alt="Detector Keypad" /></td>
<td><img src="image-url" alt="Pc Keypad" /></td>
<td>F5</td>
</tr>
<tr>
<td><img src="image-url" alt="Detector Keypad" /></td>
<td><img src="image-url" alt="Pc Keypad" /></td>
<td>F3</td>
</tr>
<tr>
<td><img src="image-url" alt="Detector Keypad" /></td>
<td><img src="image-url" alt="Pc Keypad" /></td>
<td></td>
</tr>
</tbody>
</table>
9.12 Front Axle Adjustment

Front axle adjustment procedure is launched by selecting (Figure 43) in the rear axle adjustment page after carrying out adjustment preliminary operations (see part 9.10). To adjust angles, the correct sequence is the following: CASTER – CAMBER – TOE.

**WARNING:** When entering this stage, caster values are “FROZEN”.

To “de-freeze” these values, you can press Shift+F6 at the same time. Or proceed to the summary (see part 9.13) and press F1. The program will display an additional function menu page (see part 9.14), now select “Caster Adjustment”.

Once caster values have been adjusted or, even if they are not adjusted as they are deemed to be correct, it is recommended to “FREEZE” again these values.

To repeat this operation, press Shift+F6 at the same time. A grid will be displayed onto caster values, to indicate that they are “frozen”.

Then adjust front axle
<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Keypad Image" /></td>
<td>F1 <img src="image2" alt="Keypad Image" /></td>
<td>Repeat steering procedure. (part 9.8)</td>
</tr>
<tr>
<td><img src="image3" alt="Keypad Image" /></td>
<td>F2 <img src="image4" alt="Keypad Image" /></td>
<td>“Jack-Hold” procedure (adjustment with raised wheels)</td>
</tr>
<tr>
<td><img src="image5" alt="Keypad Image" /></td>
<td>F5 <img src="image6" alt="Keypad Image" /></td>
<td>Caster/camber selection: It displays tolerance on the LED (see part 3.4.3)</td>
</tr>
<tr>
<td><img src="image7" alt="Keypad Image" /></td>
<td>F3 <img src="image8" alt="Keypad Image" /></td>
<td>It carries out toe-in adjustment with steered wheels. (See part 9.12.1)</td>
</tr>
<tr>
<td><img src="image9" alt="Keypad Image" /></td>
<td><img src="image10" alt="Keypad Image" /></td>
<td>It repeats adjustment operations (part 9.11)</td>
</tr>
</tbody>
</table>

### 9.12.1 Front toe-in adjustment with steered wheels

Front toe-in adjustment procedure with steered wheels is started by pressing F3 from front adjustment page ![Keypad Image](image11).

The following picture, requesting to steer left or right, will be shown. Press F5 to confirm.

![Figure 40](image12)
Note: Steering level indicator is displayed only to give the operator a reference of the value, which should remain within the maximum alignment reading range (about 22±24°).

After pressing F5, the page shown in Figure 41 will be displayed. “De-freeze” to enable carrying out of partial toe-ins. Use F2 (LH partial toe-in) or F3 (RH partial toe-in).

When adjustment has been completed, press F1 to return to front adjustment phase (part 9.12). The program will request to steer back toward the center before the front adjustment page is displayed (Figure 39).

![Figure 41]

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Detector Keypad" /></td>
<td><img src="image2" alt="F1 Keypad" /></td>
<td>It returns to front adjustment page display.</td>
</tr>
<tr>
<td><img src="image3" alt="Detector Keypad" /></td>
<td><img src="image4" alt="F2 Keypad" /></td>
<td>It de-freezes / freezes LH partial toe-in</td>
</tr>
<tr>
<td><img src="image5" alt="Detector Keypad" /></td>
<td><img src="image6" alt="F3 Keypad" /></td>
<td>It de-freezes / freezes RH partial toe-in</td>
</tr>
</tbody>
</table>
9.13 Summary of DIAGNOSIS and ADJUSTMENT data

This page is displayed when vehicle adjustment has been completed, after pressing F4 in the front adjustment phase, see Figure 39.

Summary of diagnosis data

Summary of adjustment carried out

<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Detector Keypad" /></td>
<td><img src="image2" alt="Pc Keypad" /></td>
<td>It displays the additional function menu. (See part 9.14)</td>
</tr>
<tr>
<td><img src="image3" alt="Detector Keypad" /></td>
<td><img src="image4" alt="Pc Keypad" /></td>
<td>It displays vehicle technical specification page.</td>
</tr>
<tr>
<td><img src="image5" alt="Detector Keypad" /></td>
<td><img src="image6" alt="Pc Keypad" /></td>
<td>Operations completed! Customer data entry and printout. (See part 9.15)</td>
</tr>
<tr>
<td><img src="image7" alt="Detector Keypad" /></td>
<td><img src="image8" alt="Pc Keypad" /></td>
<td>It returns to rear adjustment phase. (See part 9.11)</td>
</tr>
</tbody>
</table>

Figure 42
9.14 Additional Functions Menu

To carry out some additional operations or to repeat some program phases, in case they have not given satisfactory outcomes or have not been carried out at all, select F1 from the summary page (see part 9.13).

You will access an additional function menu allowing you to carry out the following procedures:

PRELIMINARY OPERATIONS: see part 9.2.1

TOE CURVE: Toe curve can be adjusted by following the displayed figures, as follows:

• Settle vehicle, press F4
• Position the special tool under front axle, press F4
• Adjust front partial toe, as recommended by the manufacturer, press F4
• Remove tool from axle, and press F4. Program will go back to the adjustment phase.

CHASSIS DIAGNOSIS: A graphic-geometrical representation of the axles of the vehicles you are working on can be displayed.

DATABASE: it enables to display the vehicle selection page (9.3) and to select a different vehicle if necessary

CASTER ADJUSTMENT: see part 9.12.

[Diagram of additional function menu]
<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Left Arrow]</td>
<td>![F1 Left Arrow]</td>
<td>It goes back to front adjustment page (part 9.12)</td>
</tr>
<tr>
<td>![Up Arrow]</td>
<td>![F2 Up Arrow]</td>
<td>It moves selection up.</td>
</tr>
<tr>
<td>![Down Arrow]</td>
<td>![F3 Down Arrow]</td>
<td>It moves selection down.</td>
</tr>
<tr>
<td>![Right Arrow]</td>
<td>![F4 Right Arrow]</td>
<td>It confirms selection.</td>
</tr>
</tbody>
</table>

### 9.15 Printout of Measurements taken

By selecting the following key from the customer data entry page, the following page will be displayed:

![Vehicle and customer data entry](image)

**Figure 44**
<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Detector Keypad" /></td>
<td><img src="image2" alt="Pc Keypad" /></td>
<td>Repeat steering procedure. (part 9.8)</td>
</tr>
<tr>
<td><img src="image3" alt="Detector Keypad" /></td>
<td><img src="image4" alt="Pc Keypad" /></td>
<td>It stores the carried out diagnosis inside a special “customer database” so as to allow test later displaying (part 9.14 on page 38)</td>
</tr>
<tr>
<td><img src="image5" alt="Detector Keypad" /></td>
<td><img src="image6" alt="Pc Keypad" /></td>
<td>It displays a print preview of the test carried out (part 9.15)</td>
</tr>
<tr>
<td><img src="image7" alt="Detector Keypad" /></td>
<td><img src="image8" alt="Pc Keypad" /></td>
<td>It goes back to start page without storing test</td>
</tr>
</tbody>
</table>

**Figure 45**

![McFarren Alignments](image9)

Vehicle Diagnosis And Adjustment  
Atlas Cyclops  
55
<table>
<thead>
<tr>
<th>Detector Keypad</th>
<th>Pc Keypad</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Image" /></td>
<td><img src="image2" alt="Image" /></td>
<td>It goes back to “vehicle data entry” phase of Figure 44</td>
</tr>
<tr>
<td><img src="image3" alt="Image" /></td>
<td><img src="image4" alt="Image" /></td>
<td>It allows selecting a printer different from the pre-set one</td>
</tr>
<tr>
<td><img src="image5" alt="Image" /></td>
<td><img src="image6" alt="Image" /></td>
<td>It sends print report to printer</td>
</tr>
<tr>
<td><img src="image7" alt="Image" /></td>
<td><img src="image8" alt="Image" /></td>
<td>It allows defining colors on the printout of out-of-tolerance data (Red to highlight them or Black NOT to highlight them)</td>
</tr>
</tbody>
</table>

A report on the performed test is printed with customer data, vehicle data before and after adjustment, vehicle technical specifications supplied by manufacturer, and any other remarks for the customer.

To access the data contained inside customer database, press F3 ![Image](image9) from the start page (see Figure 19)

**Legend of the printout example shown in Figure 46.**

1 - Logo of the manufacturer  
2 - Workshop data customization  
3 - Test date and time  
4 - Vehicle being tested and vehicle owner data  
5 - Front axle data table  
6 - Rear axle data table  
7 - Vehicle being tested manufacturing data  
8 - Vehicle being tested diagnosis data  
9 - Vehicle being tested data after adjustment
<table>
<thead>
<tr>
<th>Adjustment</th>
<th>Diagnosis</th>
<th>Target Values</th>
<th>Rear axle</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Figure 46**

Vehicle Diagnosis And Adjustment

Atlas Cyclops

[Image of a diagram showing vehicle parts and measurements]
Database Customization

Vehicle database can be personalized by creating customized groups and vehicles.

10.1 New Group Entry

To create customized groups and store them inside the database, it is necessary to display the group configuration page (see part 8.1).

Press “Insert” on the keyboard.

The following screen will be displayed:

![Groups Configuration](image)

Figure 47

Type the name of the new profile (the example Figure 48 shows “Teds Trucks”), and press F4 to confirm.
Now press F4 to enter the new “Teds Trucks” group and display the available makes with F5, as specified in Figure 18. Then display profile, always pressing F5, as described below in Figure 49. Press F1 to quit.

Note: By selecting “All makes” group using F5, a profile where all the vehicles of all the makes included in the database will be displayed.
10.2 New Group Deletion

You have to display the group configuration (see part 8.1), select the customized group you want to delete, then press “delete” \(\text{Cancel}\): press F4 to confirm.

![Groups Configuration](image)

**Figure 50**

**Warning**: If a customized group is deleted, it will no longer be possible to restore it, unless you have a database backup copy.

10.3 New Vehicle Entry

To create customized vehicles and store them inside the database, you shall first display the page of the measurements and tolerances supplied by the manufacturer of an already-existing vehicle (see part 9.4).

Press “Insert” on the keyboard: \(\text{Ins}\)

The following screen will be displayed:
As you can see in Figure 51 on the highlighted point, the make of the selected vehicle is highlighted by a red background.

You can enter or confirm the name of the make of the vehicle you want to create. Then, select and enter:

- Vehicle model and submodel name
- Manufacturing start date
- Manufacturing end date
- Rim diameter
- Front track
- Rear track
- Left wheelbase
- Right wheelbase
- Load conditions
- Tank conditions

Use the following keys for data selection:

<table>
<thead>
<tr>
<th>F4</th>
<th>Move selection to the following datum.</th>
</tr>
</thead>
<tbody>
<tr>
<td>F1</td>
<td>Move selection to the previous datum.</td>
</tr>
</tbody>
</table>
After data entry, you can delete them using the following keys:

<table>
<thead>
<tr>
<th>Key</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Canc</td>
<td>It deletes the whole selected element</td>
</tr>
<tr>
<td>←</td>
<td>It deletes the last character of the selected element</td>
</tr>
</tbody>
</table>

Once the manufacture end date has been entered and you move on the next datum, the following screen relating to load conditions will be displayed:

![Figure 52](image)

After having selected rim diameter, the following data to be entered are vehicle track and wheelbase, in the following screen:
Then enter tank and load conditions.

Now the screen will look as follows:

**Figure 53**

**Figure 54**
<table>
<thead>
<tr>
<th>3D Camera Keypad</th>
<th>Pc Keyboard</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image1" alt="Left Arrow" /></td>
<td><img src="image2" alt="F1" /></td>
<td>Goes back to the Introduction page. (see Figure 10)</td>
</tr>
<tr>
<td><img src="image3" alt="Up Arrow" /></td>
<td><img src="image4" alt="F2" /></td>
<td>Moves selection up.</td>
</tr>
<tr>
<td><img src="image5" alt="Down Arrow" /></td>
<td><img src="image6" alt="F3" /></td>
<td>Moves selection down.</td>
</tr>
</tbody>
</table>

As you can see from the zoom on the right side of Figure 54, you will have to specify if the point datum refers to can be adjusted or not.

| | The point to which the data refer can be adjusted. To define it as not-adjustable, press: |
| | The point to which the data refer cannot be adjusted. To define it as adjustable, press: |
| | Once the desired option has been selected, press: |

Once angle “adjustability” has been specified, you can enter the **graphic animations**. Select the correct image or animation with keys ![Down Arrow](image7) ![Up Arrow](image8), then press “Enter” to confirm.

Now you shall enter vehicle standard tolerance values as for:

**FRONT AXLE:**
- Toe
- Camber
- Caster
- Kingpin
- Included angle
- Max. steering

**REAR AXLE:**
- Toe
- Camber
- Thrust angle

Select data as described above, and enter values.
**Warning:** To separate whole values from decimals, try using a “dot” 🈞️ or a “comma” 🈞️.

When you have completed entering values, the following screen will be displayed. You will have to select an option:

Press F4 ✅ to confirm and create the customized vehicle.

If vehicle database is displayed, you can see that the just-created customized vehicle is present; it is listed under a separate make, in alphabetical order, written in italic.

Using the same procedure, you can edit the values of a customized vehicle without having to create a new one. The final screen will be like the one of Figure 55 with the additional item:

“Edit customized vehicle”

Select this option to edit vehicle data.
10.4 Customized Vehicle Deletion

You have to display vehicle database, and select the customized vehicle you wish to delete, then press Ctrl + Delete:

**Warning**: If a customized vehicle is deleted, it will no longer be possible to restore it, unless you have a database backup copy.
Program And Database Protection

The Atlas Cyclops features a PC with SMART CARD reader.

This SMART CARD, inserted inside reader, allows program operation, and enables access to vehicle DATABASE.

Every machine has its own unique SMARTCARD that cannot be replaced with the SMARTCARD of another machine for whatever reason.

Should this SMARTCARD be removed or replaced, programs will display an error message, such as Figure 57, and will not give the authorization to continue.
Databases can be updated by downloading files from Internet.
Contact your retailer for further details on the download from the manufacturer’s web site.

11.1 DATABASE Management

To update the database, proceed as follows:
Select “Database Management” option from program configuration menu (see part 8) as specified in Figure 58, and press F4 to continue.

Figure 58
When a USB flash disc key is inserted (such as the one supplied with the machine, and containing system Back-Up), the keys for database management are displayed, as shown in Figure 60.
**F2** → Export certificate on USB flash disc. Customer shall send it to the manufacturer so that a release key can be prepared (as an alternative to the communication of customer’s SMARTCARD serial number).

**F3** → Manufacturer sends the release code (called Token) to the customer after having checked the fulfillment of requirements (such as payment of the new Database). This “Token” file shall be pasted inside the USB flash disk ROOT and, by selecting this key, the Token is imported by the PC through the right path so that the new database is released.

**F4** → Allows copying the correct path of the DATABASE file previously downloaded from internet and pasted inside the USB flash disk ROOT. Updated databases shall then be released through “Token” import.
12.1 Data transmission/reception error from 3D cameras / failed target identification.

During data transmission/reception between 3D cameras and cabin, the following page may be displayed:

This may mean that there is a transmission/reception failure due to one or several of the following problems:

- Failure or radio interference in the transmission system with 3D cameras.
- 3D camera/s is/are broken or off.

<table>
<thead>
<tr>
<th>NO communication</th>
<th>Communication OK</th>
</tr>
</thead>
<tbody>
<tr>
<td>If one or both symbols are GREY, it means that there is a transmission/reception failure.</td>
<td>Check that the Bluetooth communication of 3D cameras becomes active (both symbols should be BLUE).</td>
</tr>
</tbody>
</table>
If both symbols are BLUE, the error in Figure 61 may signal a failed identification of the target/s, caused by one or more of the problems listed below:

- Camera covered (cap on).
- Obstruction between target and camera.
- Target not mounted or not in the correct position (see part 9.2.2)
- Camera broken

If the cause of failure is eliminated (ex. obstruction between target and camera is removed) the error page will immediately disappear, and the measurement page will be displayed again. If the problem continues, check system hardware by switching machine off. Of course, it is not recommended to abruptly power cabin off; follow the correct switching off procedure:

- Press “Esc” on keyboard to go back to the introduction page (see part 10).
- Switch machine off following the usual procedure (see part 6.2).
Some of the most common problems that could arise on wheel aligners are listed here below. Atlas Equipment declines all liability for injury or damage to persons, animals and properties caused by the intervention of unauthorized personnel, and by the use of non-original spare parts.

Before doing any operation on the system, always disconnect the power supply.

In case of doubt, do not interpret, but contact Atlas Equipment technical assistance in order to obtain instructions suitable for performing operations in total safety.

<table>
<thead>
<tr>
<th>TROUBLE</th>
<th>CAUSE</th>
<th>REMEDY</th>
</tr>
</thead>
<tbody>
<tr>
<td>NO OPERATION</td>
<td>• No main voltage</td>
<td>• Check main voltage</td>
</tr>
<tr>
<td></td>
<td>• Interrupted protection fuses</td>
<td>• Check protection fuses</td>
</tr>
<tr>
<td>Monitor does not work</td>
<td>• No supply voltage</td>
<td>• Check power cable connection</td>
</tr>
<tr>
<td></td>
<td>• No video signal</td>
<td>• Check video signal cable connection between PC and monitor</td>
</tr>
<tr>
<td>PC cannot be switched on</td>
<td>• No supply voltage</td>
<td>• Check PC ON/OFF switch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check power cable connection</td>
</tr>
<tr>
<td>Printer does not work</td>
<td>• No supply voltage</td>
<td>• Check ON/OFF voltage</td>
</tr>
<tr>
<td>(see also printer user’s manual)</td>
<td>• No signal</td>
<td>• Check power cable connection</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check printer signal cable connection with PC</td>
</tr>
</tbody>
</table>
WARNING! Before doing any maintenance job, the machine will have to be disconnected from power.

To clean plastic panels or surfaces use alcohol (AVOID USING LIQUIDS CONTAINING SOLVENTS). DISPLAY shall be cleaned with a dry cloth; if very dirty, clean it with a moist cloth, then dry it. Do not spray the alcohol directly on the control panel and do not clean using strong jets of compressed air.

Keep optical unit methacrylate filters clean using a slightly moist cloth, do not use solvents;

Printer cleaning, cartridge replacement and any other maintenance operation on printer are described in the manual supplied with the printer itself. Always refer to this manual before carrying out any maintenance operation on printer.
**Storage And Scrapping**

**Storage** - If the machine has to be stored for a long period of time, disconnect all supply lines and protect the display screen, which could be damaged by excessive dust.

Grease any parts liable to be damaged by dryness.

**Scrapping** - If the machine is to be no longer used, it must be made inoperative:

All those parts that could represent a potential hazard risk must be correctly disposed of. Dispose of parts according to category.

Scrap as iron scrap through authorized channels.

Parts considered as special waste must be removed and split up according to type and then disposed of through authorized channels according to applicable regulations.
WARNING: It is strictly forbidden to tamper with, alter, or even remove machine identification plate; do not cover it with temporary panels, etc... as it shall always be clearly visible.

Said plate must always be kept clean.

CAUTION: Should the plate be accidentally damaged (removed from the machine damaged or even partially illegible) immediately inform the manufacturer.